

# **MANE 4240 & CIVL 4240**

## **Introduction to Finite Elements**

**Prof. Suvranu De**

### **Numerical Integration in 2D**

## **Reading assignment:**

**Lecture notes, Logan 10.4**

## **Summary:**

- Gauss integration on a 2D square domain
- Integration on a triangular domain
- Recommended order of integration
- “Reduced” vs “Full” integration; concept of “spurious” zero energy modes/ “hour-glass” modes

## 1D quadrature rule recap

$$I = \int_{-1}^1 f(\xi) d\xi \approx \sum_{i=1}^M W_i f(\xi_i)$$

Weight

Integration point

Choose the integration points **and** weights to maximize accuracy

Newton-Cotes

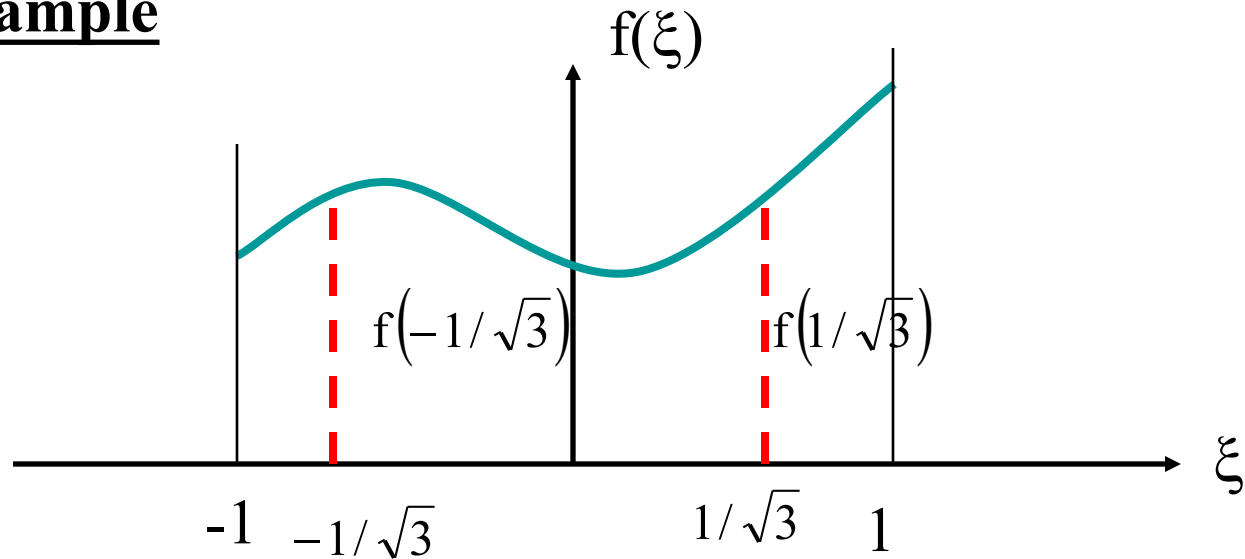
Gauss quadrature

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1. 'M' integration points are necessary to exactly integrate a polynomial of degree 'M-1'
2. More expensive

1. 'M' integration points are necessary to exactly integrate a polynomial of degree '2M-1'
2. Less expensive
3. Exponential convergence, error proportional to  $\left(\frac{1}{2M}\right)^{2M}$

## Example

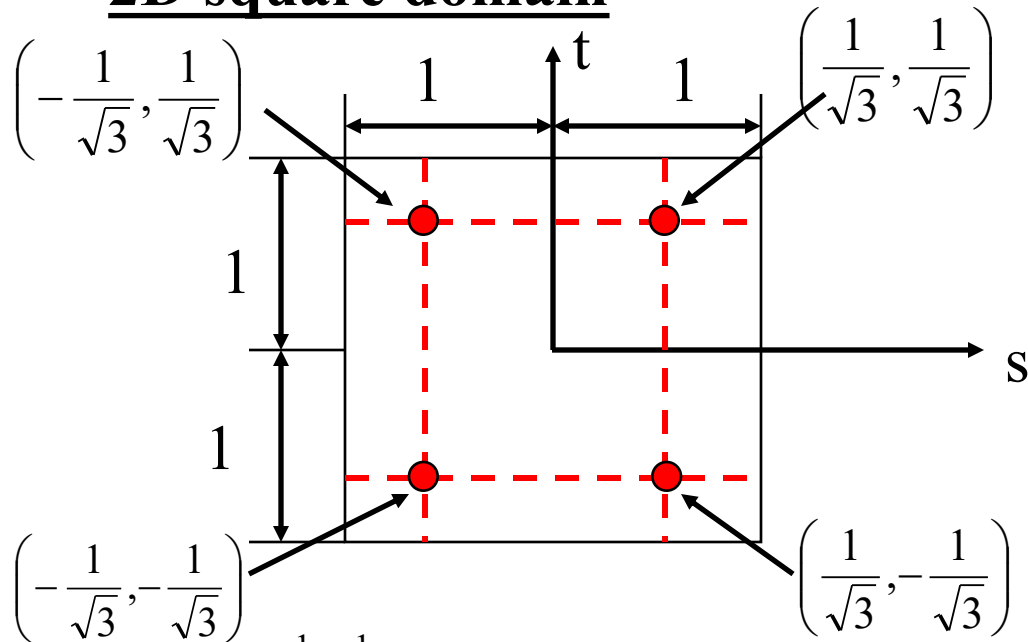


A 2-point Gauss quadrature rule

$$\int_{-1}^1 f(\xi) d\xi \approx f\left(\frac{1}{\sqrt{3}}\right) + f\left(-\frac{1}{\sqrt{3}}\right)$$

is **exact** for a polynomial of degree 3 or less

## 2D square domain



$$I = \int_{-1}^1 \int_{-1}^1 f(s, t) ds dt$$

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$$\approx \int_{-1}^1 \left( \sum_{j=1}^M W_j f(s, t_j) \right) ds \quad \text{Using 1D Gauss rule to integrate along 't'}$$

$$\approx \sum_{i=1}^M \sum_{j=1}^M W_i W_j f(s_i, t_j) \quad \text{Using 1D Gauss rule to integrate along 's'}$$

$$= \sum_{i=1}^M \sum_{j=1}^M W_{ij} f(s_i, t_j) \quad \text{Where } W_{ij} = W_i W_j$$

For M=2

$$I \approx \sum_{i=1}^2 \sum_{j=1}^2 W_{ij} f(s_i, t_j) \quad W_{ij} = W_i W_j = 1$$
$$= f\left(\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}\right) + f\left(-\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}\right) + f\left(-\frac{1}{\sqrt{3}}, -\frac{1}{\sqrt{3}}\right) + f\left(\frac{1}{\sqrt{3}}, -\frac{1}{\sqrt{3}}\right)$$

Number the Gauss points IP=1,2,3,4

$$I = \int_{-1}^1 \int_{-1}^1 f(s, t) ds dt \approx \sum_{IP=1}^4 W_{IP} f_{IP}$$

The rule

$$I = \int_{-1}^1 \int_{-1}^1 f(s, t) ds dt \approx \sum_{i=1}^M \sum_{j=1}^M W_{ij} f(s_i, t_j)$$

Uses  **$M^2$  integration points** on a nonuniform grid inside the parent element and is **exact for a polynomial of degree  $(2M-1)$**  i.e.,

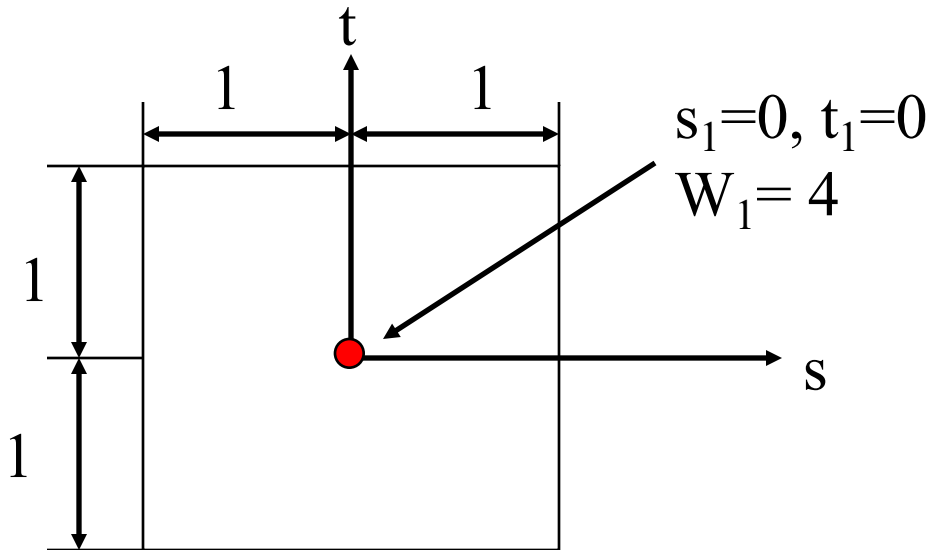
$$\int_{-1}^1 \int_{-1}^1 s^\alpha t^\beta ds dt \stackrel{\text{exact}}{=} \sum_{i=1}^M \sum_{j=1}^M W_{ij} s_i^\alpha t_j^\beta \quad \text{for } \alpha + \beta \leq 2M - 1$$

**A  $M^2$  -point rule is exact for a complete polynomial of degree  $(2M-1)$**

CASE I: M=1 (One-point GQ rule)

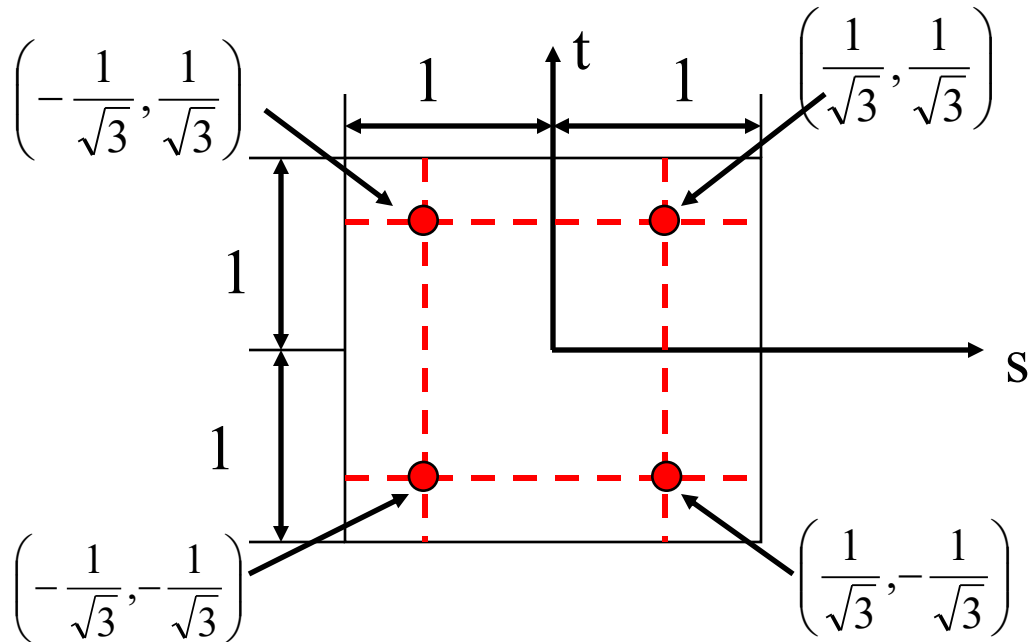
$$I = \int_{-1}^1 \int_{-1}^1 f(s, t) ds dt \approx 4 f(0, 0)$$

is exact for a product of two linear polynomials





## CASE II: M=2 (2x2 GQ rule)

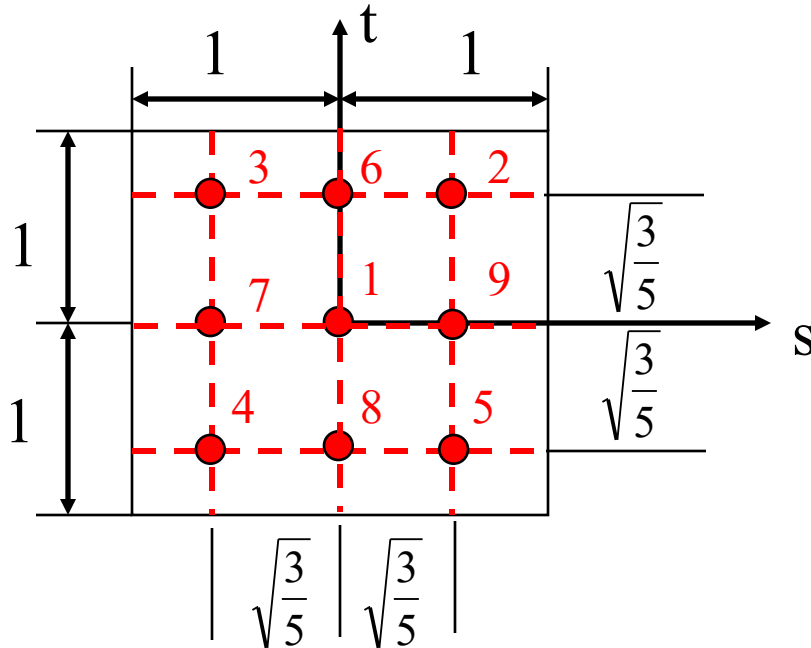


$$I \approx \sum_{i=1}^2 \sum_{j=1}^2 W_{ij} f(s_i, t_j)$$

$$= f\left(\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}\right) + f\left(-\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}\right) + f\left(-\frac{1}{\sqrt{3}}, -\frac{1}{\sqrt{3}}\right) + f\left(\frac{1}{\sqrt{3}}, -\frac{1}{\sqrt{3}}\right)$$

is exact for a product of two  
cubic polynomials

### CASE III: M=3 (3x3 GQ rule)



$$W_1 = \frac{64}{81},$$

$$W_2 = W_3 = W_4 = W_5 = \frac{25}{81}$$

$$W_6 = W_7 = W_8 = W_9 = \frac{40}{81}$$

$$I = \int_{-1}^1 \int_{-1}^1 f(s, t) ds dt \approx \sum_{i=1}^3 \sum_{j=1}^3 W_{ij} f(s_i, t_j)$$

is exact for a product of two 1D polynomials of degree 5

# Examples

If  $f(s, t) = 1$

$$I = \int_{-1}^1 \int_{-1}^1 f(s, t) \, ds dt = 4$$

A **1-point GQ scheme** is sufficient

If  $f(s, t) = s$

$$I = \int_{-1}^1 \int_{-1}^1 f(s, t) \, ds dt = 0$$

A **1-point GQ scheme** is sufficient

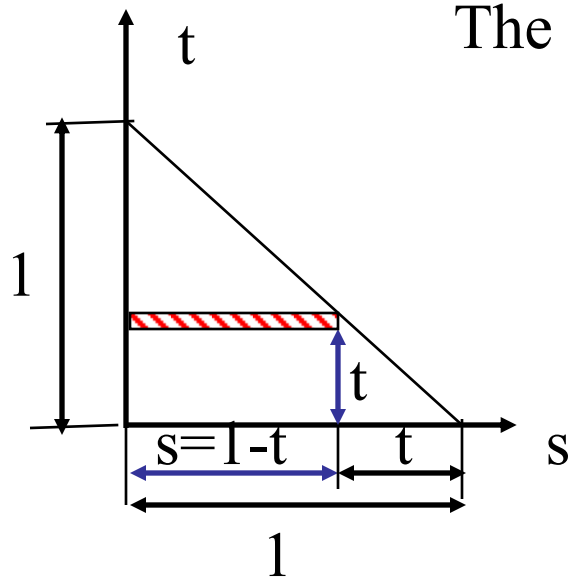
If  $f(s, t) = s^2 t^2$

$$I = \int_{-1}^1 \int_{-1}^1 f(s, t) \, ds dt = \frac{4}{9}$$

A **3x3 GQ scheme** is sufficient

## 2D Gauss quadrature for triangular domains

Remember that the **parent element** is a right angled triangle with unit sides



The type of integral encountered

$$I = \int_{t=0}^1 \int_{s=0}^{1-t} f(s, t) \, ds dt$$

$$I = \int_{t=0}^1 \int_{s=0}^{1-t} f(s, t) \, ds dt$$
$$\approx \sum_{IP=1}^M W_{IP} f_{IP}$$

## Constraints on the weights

if  $f(s,t)=1$

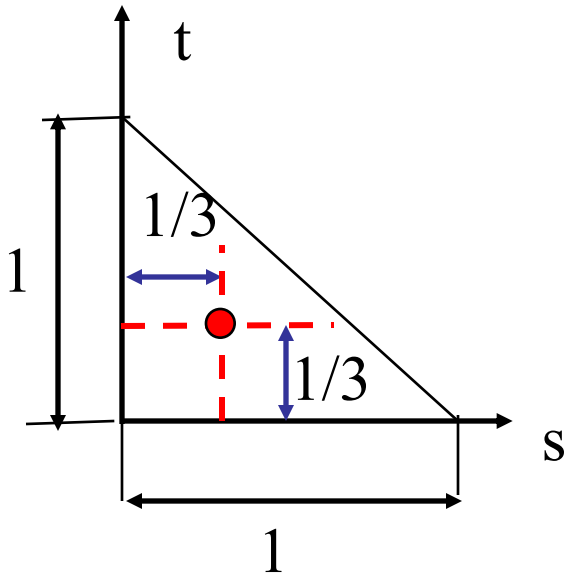
$$I = \int_{t=0}^1 \int_{s=0}^{1-t} f(s,t) \, ds dt = \frac{1}{2}$$

$$= \sum_{IP=1}^M W_{IP}$$

$$\therefore \sum_{IP=1}^M W_{IP} = \frac{1}{2}$$

Example 1. A  $M=1$  point rule is exact for a polynomial

$$f(s, t) \sim 1$$



$$I \approx \frac{1}{2} f\left(\frac{1}{3}, \frac{1}{3}\right)$$

Why?

Assume

$$f(s, t) = \alpha_1 + \alpha_2 s + \alpha_3 t$$

Then

$$\int_{t=0}^1 \int_{s=0}^{1-t} f(s, t) \, ds dt = \frac{1}{2} \alpha_1 + \frac{1}{3!} \alpha_2 + \frac{1}{3!} \alpha_3$$

But

$$\int_{t=0}^1 \int_{s=0}^{1-t} f(s, t) \, ds dt = W_1 f(s_1, t_1)$$

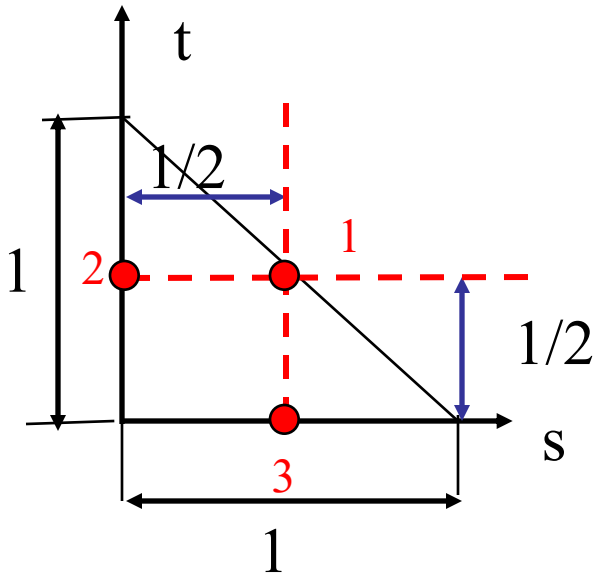
$$\therefore \frac{1}{2} \alpha_1 + \frac{1}{3!} \alpha_2 + \frac{1}{3!} \alpha_3 = W_1 (\alpha_1 + \alpha_2 s_1 + \alpha_3 t_1)$$

Hence

$$W_1 = \frac{1}{2}; W_1 s_1 = \frac{1}{3!}; W_1 t_1 = \frac{1}{3!}$$

Example 2. A  $M=3$  point rule is exact for a complete polynomial of degree 2

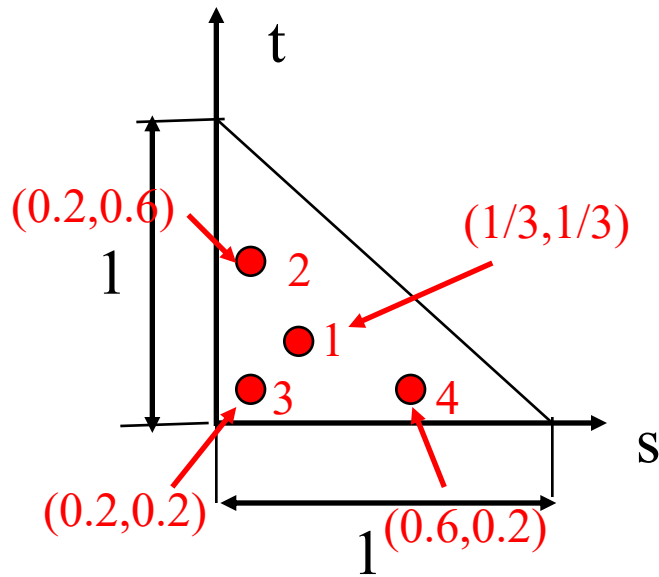
$$f(s, t) \sim 1 + s + t + s^2 + st + t^2$$



$$I \approx \frac{1}{6} f\left(\frac{1}{2}, \frac{1}{2}\right) + \frac{1}{6} f\left(\frac{1}{2}, 0\right) + \frac{1}{6} f\left(0, \frac{1}{2}\right)$$



Example 4. A M=4 point rule is exact for a complete polynomial of degree 3

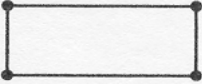





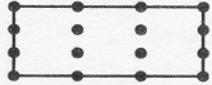
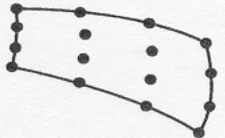


$$f(s, t) \sim \begin{matrix} 1 \\ s & t \\ s^2 & st & t^2 \\ s^3 & s^2t & st^2 & t^3 \end{matrix}$$

$$I \approx -\frac{27}{96} f\left(\frac{1}{3}, \frac{1}{3}\right) + \frac{25}{96} f(0.2, 0.6) + \frac{25}{96} f(0.2, 0.2) + \frac{25}{96} f(0.6, 0.2)$$

**TABLE 5.9** Recommended full Gauss numerical integration orders for the evaluation of isoparametric displacement-based element matrices (use of Table 5.7)

**Recommended  
order of  
integration  
“Finite Element  
Procedures”  
by K. –J. Bathe**

	Two-dimensional elements (plane stress, plane strain and axisymmetric conditions)	Integration order
4-node		2 × 2
4-node distorted		2 × 2
8-node		3 × 3
8-node distorted		3 × 3
9-node		3 × 3
9-node distorted		3 × 3
16-node		4 × 4
16-node distorted		4 × 4

## “Reduced” vs “Full” integration

**Full integration:** Quadrature scheme sufficient to provide exact integrals of all terms of the stiffness matrix if the element is geometrically undistorted.

**Reduced integration:** An integration scheme of lower order than required by “full” integration.

**Recommendation:** Reduced integration is NOT recommended.

# Which order of GQ to use for full integration?

To compute the stiffness matrix we need to evaluate the following integral

$$\underline{k} = \int_{-1}^1 \int_{-1}^1 \underline{B}^T \underline{D} \underline{B} \det(\underline{J}) \, ds dt$$

For an “undistorted” element  $\det(\underline{J}) = \text{constant}$

Example : 4-noded parallelogram

$$N_i \sim \begin{matrix} 1 & & \\ & s & t \\ & & st \end{matrix}$$

$$\underline{B} \sim \begin{matrix} 1 & & \\ s & & t \end{matrix}$$

$$\underline{B}^T \underline{D} \underline{B} \sim \begin{matrix} & & 1 \\ & s & t \\ s^2 & st & t^2 \end{matrix}$$

Hence,  $2M-1=2$

$$M=3/2$$

Hence we need at least a 2x2 GQ scheme

Example 2: **8-noded Serendipity element**

$$N_i \sim \begin{matrix} & & & 1 \\ & & s & t \\ & s^2 & st & t^2 \\ s^2t & & st^2 & \end{matrix}$$

$$\underline{B} \sim \begin{matrix} & & & 1 \\ & & s & t \\ s^2 & & st & t^2 \end{matrix}$$



## Reduced integration leads to rank deficiency of the stiffness matrix and “spurious” zero energy modes

### “Spurious” zero energy mode/ “hour-glass” mode

The strain energy of an element

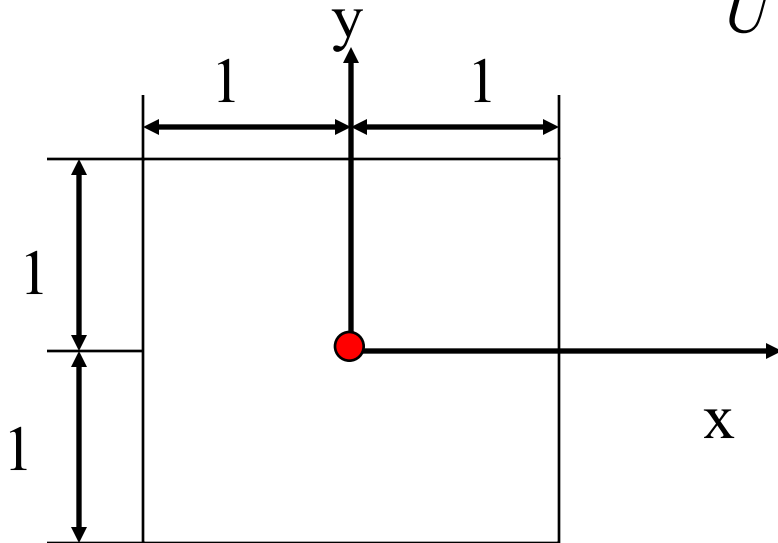
$$U = \frac{1}{2} \underline{d}^T \underline{k} \underline{d} = \frac{1}{2} \int_{V^e} \underline{\varepsilon}^T \underline{D} \underline{\varepsilon} dV$$

Corresponding to a rigid body mode,  $\underline{\varepsilon} = \underline{0} \Rightarrow U = 0$

If  $U=0$  for a mode  $\underline{d}$  that is different from a rigid body mode, then  $\underline{d}$  is known as a “spurious” zero energy mode or “hour-glass” mode

Such a mode is **undesirable**

## Example 1. 4-noded element



$$U = \frac{1}{2} \int_{V^e} \underline{\underline{\varepsilon}}^T \underline{\underline{D}} \underline{\underline{\varepsilon}} dV \approx \sum_{i=1}^{NGAUSS} W_i \left( \underline{\underline{\varepsilon}}^T \underline{\underline{D}} \underline{\underline{\varepsilon}} \right)_i$$

**Full integration:** NGAUSS=4

Element has 3 zero energy (rigid body) modes

**Reduced integration:** e.g.,  
NGAUSS=1

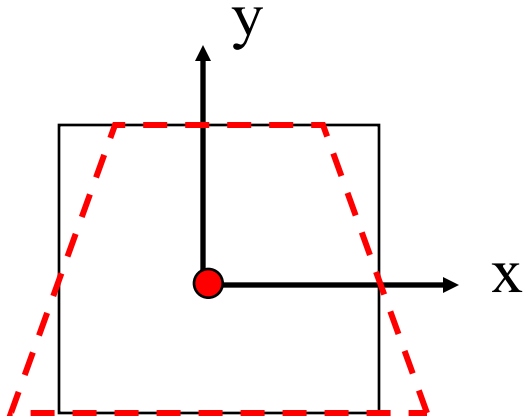
$$U \approx 4 \left( \underline{\underline{\varepsilon}}^T \underline{\underline{D}} \underline{\underline{\varepsilon}} \right)_{\substack{x=0 \\ y=0}}$$



Consider 2 displacement fields

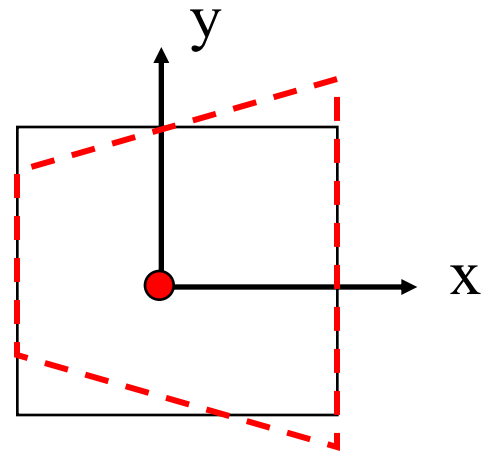
$$u = C xy$$

$$v = 0$$



$$u = 0$$

$$v = C xy$$

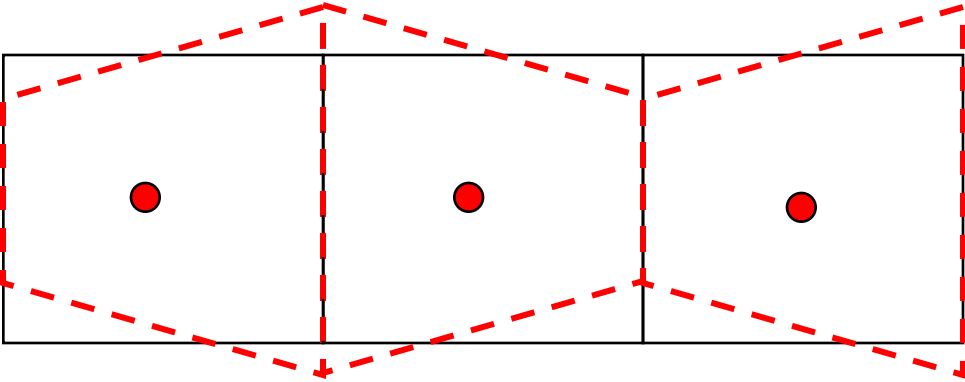
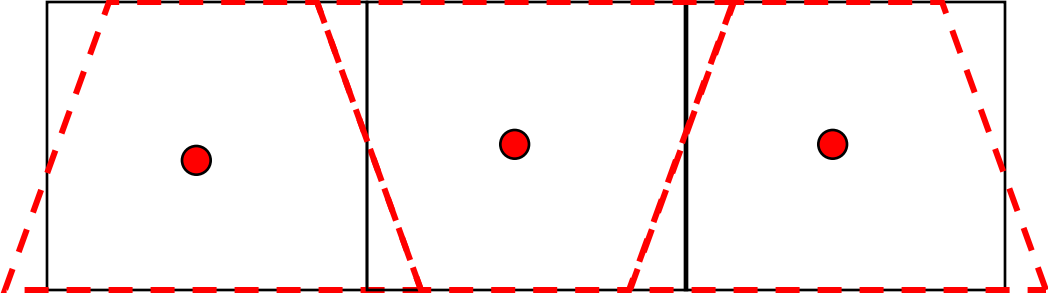


$$\text{At } x = y = 0 \quad \varepsilon_x = \varepsilon_y = \gamma_{xy} = 0$$

$$\Rightarrow U = 0$$

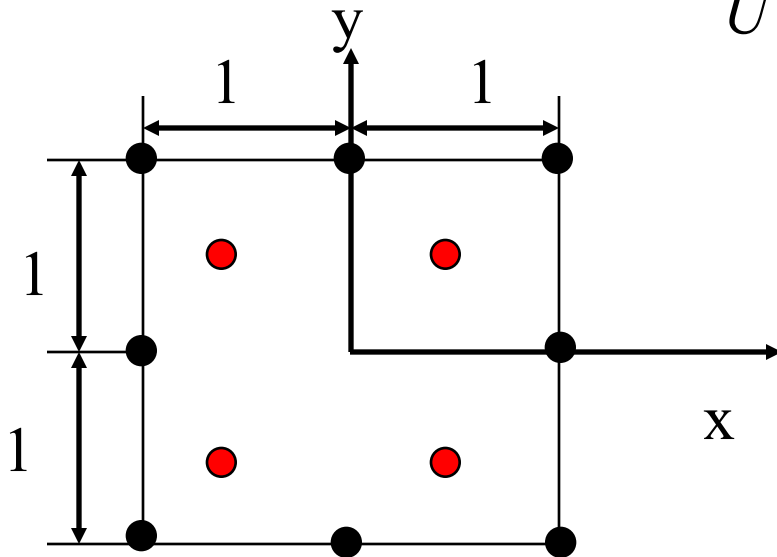
We have therefore 2 hour-glass modes.

# Propagation of hour-glass modes through a mesh



## Example 2. 8-noded serendipity element

$$U = \frac{1}{2} \int_{V^e} \underline{\varepsilon}^T \underline{D} \underline{\varepsilon} dV \approx \sum_{i=1}^{NGAUSS} W_i \left( \underline{\varepsilon}^T \underline{D} \underline{\varepsilon} \right)_i$$



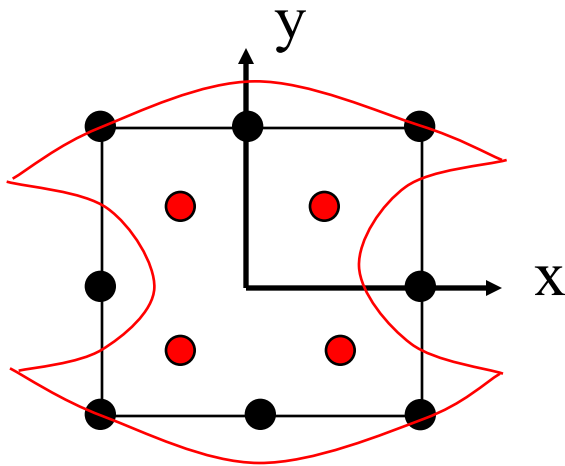
**Full integration:** NGAUSS=9  
 Element has 3 zero energy (rigid body) modes

**Reduced integration:** e.g.,  
 NGAUSS=4

Element has one spurious zero energy mode corresponding to the following displacement field

$$u = C x (y^2 - 1/3)$$

$$v = -C y (x^2 - 1/3)$$



Show that the strains corresponding to this displacement field are all zero at the 4 Gauss points

**Elements with zero energy modes introduce uncontrolled errors and should NOT be used in engineering practice.**